



# GRAYHILL

## SERIES 60AD

Optical Encoder with integrated Joystick and Pushbutton

### FEATURES

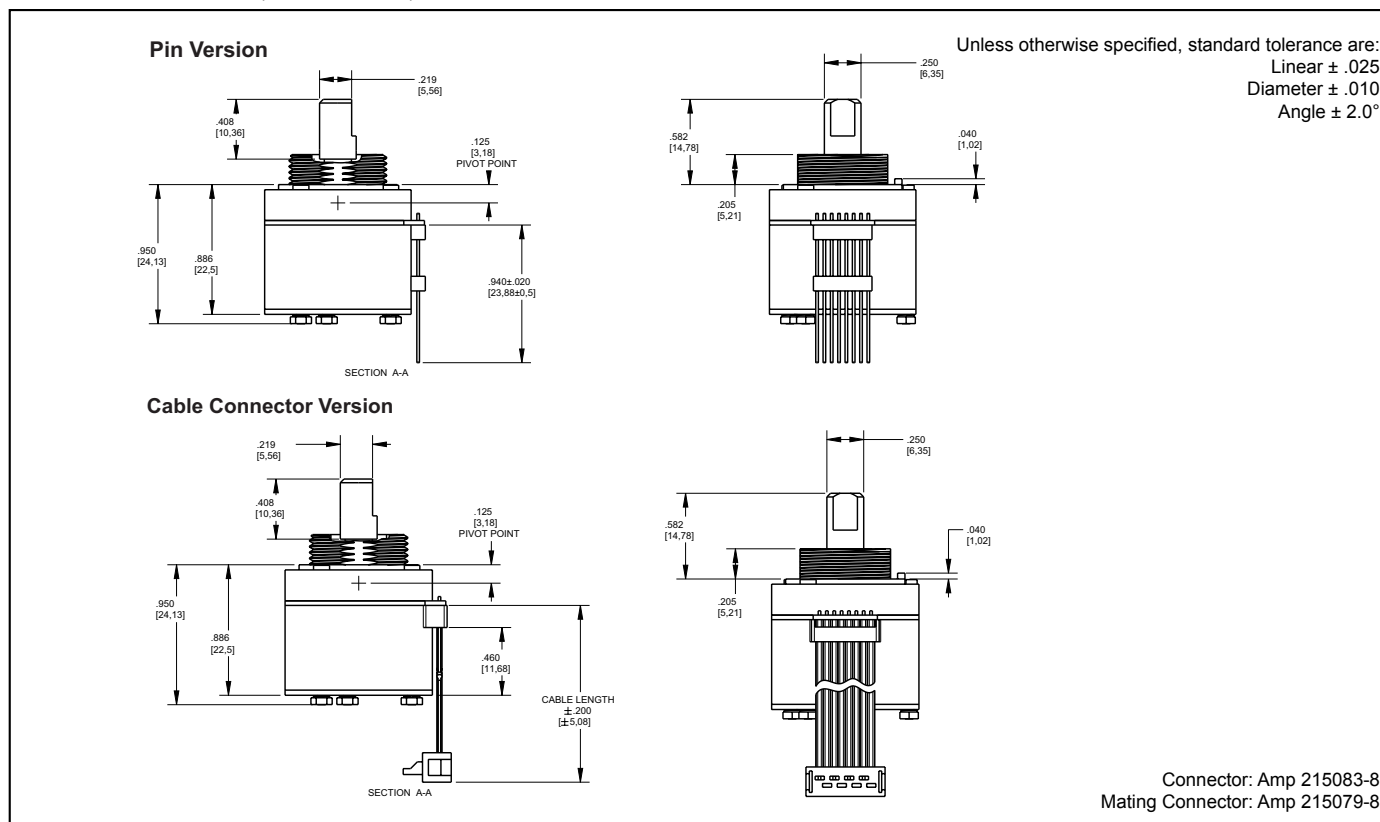
- Dome contacts provide excellent tactile feedback in all directions
- Choices of actuation force, cable length and termination
- Customized solutions available

### APPLICATIONS

- Aerospace
- Automotive
- Medical devices



### DIMENSIONS in inches (and millimeters)



### ORDERING INFORMATION

**60AD18-4-M-060S**

Angle of Throw: 18= 18° or 20 positions  
Joystick: 4= Four contacts & directions;  
8= Four contacts & eight directions

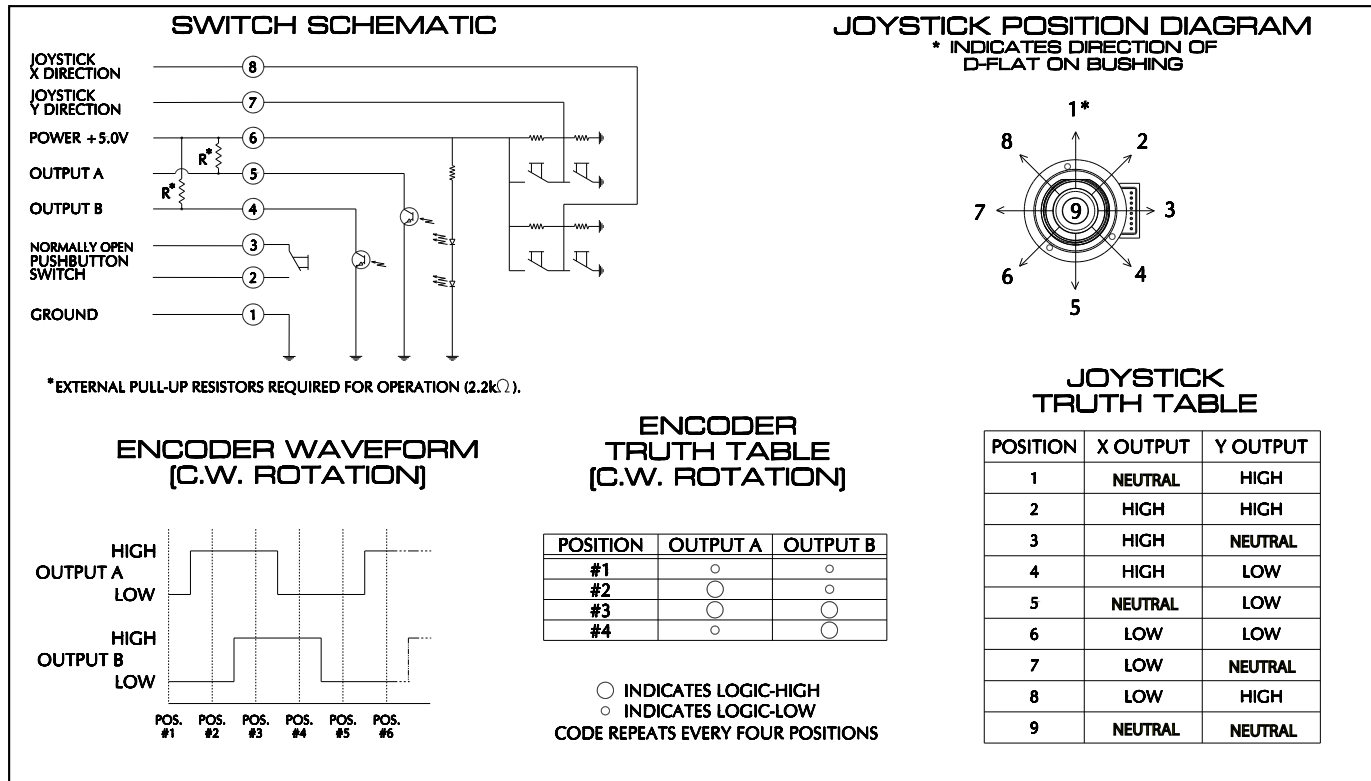
Termination: 0.050" center P= pin header; C= connector; S= stripped cable  
Cable Length: .020 thru .250 in 1/2 inch increments, .060= 6.0 inch cable  
Force Option: (see table) L=low, M=medium, H=high

		OPTION		
		L	M	H
1	ACTUATION FORCE (JOYSTICK) [g]	550±200	725±200	1050±250
2	ACTUATION FORCE (PUSHBUTTON) [g]	625±200	800±200	1100±250
3	AVERAGE ROTATIONAL TORQUE [in-oz]	1.50±0.75	3.50±1.75	5.00±2.00

For prices and custom configurations, contact a local sales office, an authorized distributor, or Grayhill's sales department.



## JOYSTICK OPERATION + ENCODER WAVEFORM AND TRUTH TABLE Standard Quadrature 2-Bit Code



## SPECIFICATIONS

### Rotary Specifications

**Operating Voltage:** 5.00  $\pm$  0.25 Vdc  
**Supply Current:** 20mA max at 5 Vdc  
**Minimum Sink Current:** 2.0mA at 5 Vdc  
**Power Consumption:** 100 mW max at 5 Vdc  
**Output:** Open collector phototransistor, 2.2k  $\Omega$  external pull-up resistors are required  
**Output Code:** 2-Bit quadrature, channel A leads channel B by 90° in clockwise rotation  
**Logic Output Characteristics:**  
 High: No less than 3.5 Vdc  
 Low: No greater than 1.0 Vdc  
**Mechanical Life:** 1 million rotational cycles (through all positions and a full return)  
**Rotational Torque:** see table  
**Maximum Rotational Speed:** 100 RPM  
**Mounting Torque:** 15 in-lbs. maximum  
**Shaft Push/Pull Out Force:** 45 lbs min.  
**Shaft Side-Load Force:** 20 lbs. max.  
**Terminal Strength:** 15 lbs pull-out force min.

### Pushbutton Specifications

**Rating:** 10 mA at 5 Vdc resistive  
**Contact Resistance:** less than 10 ohms  
**Contact Bounce:** < 4ms make, <10 ms break  
**Mechanical Life:** 1 million actuations min.  
**Actuation Force:** see table  
**Pushbutton Travel:** .027  $\pm$  .010 in.

### Joystick Specifications

**Supply Current:** 5mA max  
**Output Code:** 2-Bit  
**Logic Output Characteristics:**  
 Neutral Position: 2.5  $\pm$  0.5 Vdc  
 High-State Position: >4.5 Vdc  
 Low-State Position: <0.5 Vdc  
**Mechanical Life:** 500k cycles min.  
**Actuation Force:** see table  
**Angle of Throw:** 3.5° +2°/-1°

### Environmental Ratings

**Operating Temp. Range:** -40°C to 85°C  
**Storage Temp. Range:** -55°C to 100°C  
**Relative Humidity:** 96 hours at 90-95% humidity at 40°C  
**Vibration:** Harmonic motion with amplitude of 15g, within 10 to 2000 Hz for 12 hours  
**Mechanical Shock:**  
 Test 1: 100g for 6ms half-sine wave with a velocity change of 12.3 ft/s  
 Test 2: 100g for 6ms sawtooth wave with a velocity change of 9.7 ft/s

### Materials and Finishes

**Detent Housing:** Nylon 6/10  
**Shaft:** Nylon 6/10  
**Shaft Insert:** 303 stainless steel  
**Joystick Housing:** Nylon 6,10  
**Centering Plate:** Nylon 6,10  
**Detent Balls:** Carbon steel  
**Detent Springs:** Music wire  
**Dome Contacts:** Stainless steel  
**Dome Housings:** Polycarbonate over brass-lead frame  
**Dome Retainers:** Nylon 6,0; 30% glass-filled  
**Joystick Actuators:** Polyphthalamide; 50% glass filled  
**Pushbutton Dome Retainer:** Polycarbonate  
**Printed Circuit Board:** NEMA grade FR-4.  
 Glass-cloth epoxy, double clad with copper  
**Infrared Emitter:** Gallium arsenide  
**Phototransistor:** Planar silicon  
**Resistors:** Metal oxide on ceramic substrate  
**Solder:** 95.5% SN, 3% AG, 0.5% CU

### OPTIONS

Contact Grayhill for custom terminations, rotational torque, number of positions, shaft configurations, and resolutions.